

# Thyristor Modules

## Thyristor/Diode Modules

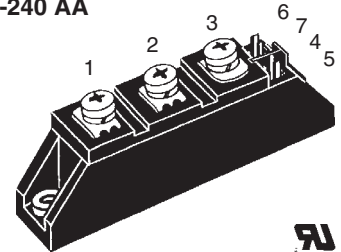
$$I_{TRMS} = 2 \times 180 \text{ A}$$

$$I_{TAVM} = 2 \times 115 \text{ A}$$

$$V_{RRM} = 800-1800 \text{ V}$$

| $V_{RSM}$<br>$V_{DSM}$<br>V | $V_{RRM}$<br>$V_{DRM}$<br>V | Type      |               |     |           |               |     |  |
|-----------------------------|-----------------------------|-----------|---------------|-----|-----------|---------------|-----|--|
|                             |                             | Version   | 1 B           | 8 B | Version   | 1 B           | 8 B |  |
| 900                         | 800                         | MCC 72-08 | io1 B / io8 B |     | MCD 72-08 | io1 B / io8 B |     |  |
| 1300                        | 1200                        | MCC 72-12 | io1 B / io8 B |     | MCD 72-12 | io1 B / io8 B |     |  |
| 1500                        | 1400                        | MCC 72-14 | io1 B / io8 B |     | MCD 72-14 | io1 B / io8 B |     |  |
| 1700                        | 1600                        | MCC 72-16 | io1 B / io8 B |     | MCD 72-16 | io1 B / io8 B |     |  |
| 1900                        | 1800                        | MCC 72-18 | io1 B / io8 B |     | MCD 72-18 | io1 B / io8 B |     |  |

TO-240 AA

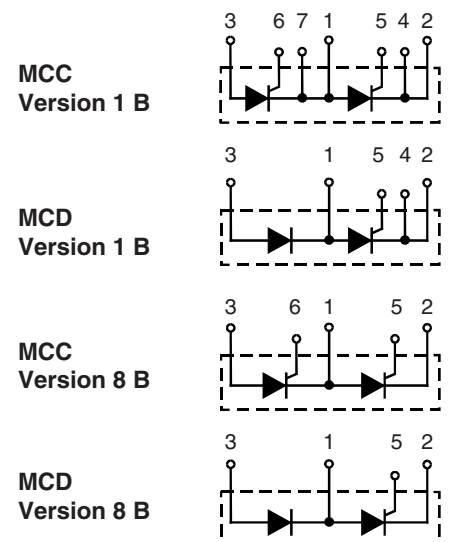


| Symbol                                       | Conditions                                                                                                                 | Maximum Ratings                                                         |                                                                                          |
|----------------------------------------------|----------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------|------------------------------------------------------------------------------------------|
| $I_{TRMS}, I_{FRMS}$<br>$I_{TAVM}, I_{FAVM}$ | $T_{VJ} = T_{VJM}$<br>$T_C = 63^\circ\text{C}; 180^\circ \text{ sine}$<br>$T_C = 85^\circ\text{C}; 180^\circ \text{ sine}$ | 180<br>115<br>85                                                        | A<br>A<br>A                                                                              |
| $I_{TSM}, I_{FSM}$                           | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0$                                                                                   | $t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$ | 1700<br>1800<br>A<br>A                                                                   |
|                                              | $T_{VJ} = T_{VJM}$<br>$V_R = 0$                                                                                            | $t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$ | 1540<br>1640<br>A<br>A                                                                   |
| $\int i^2 dt$                                | $T_{VJ} = 45^\circ\text{C}$<br>$V_R = 0$                                                                                   | $t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$ | 14 450<br>13 500<br>$\text{A}^2\text{s}$<br>$\text{A}^2\text{s}$                         |
|                                              | $T_{VJ} = T_{VJM}$<br>$V_R = 0$                                                                                            | $t = 10 \text{ ms (50 Hz), sine}$<br>$t = 8.3 \text{ ms (60 Hz), sine}$ | 11 850<br>11 300<br>$\text{A}^2\text{s}$<br>$\text{A}^2\text{s}$                         |
| $(di/dt)_{cr}$                               | $T_{VJ} = T_{VJM}$<br>$f = 50 \text{ Hz}; t_p = 200 \mu\text{s}$                                                           | repetitive, $I_T = 250 \text{ A}$                                       | 150<br>$\text{A}/\mu\text{s}$                                                            |
|                                              | $V_D = \frac{2}{3} V_{DRM}$<br>$I_G = 0.45 \text{ A}$<br>$di_G/dt = 0.45 \text{ A}/\mu\text{s}$                            | non repetitive, $I_T = I_{TAVM}$                                        | 500<br>$\text{A}/\mu\text{s}$                                                            |
| $(dv/dt)_{cr}$                               | $T_{VJ} = T_{VJM};$<br>$R_{GK} = \infty; \text{method 1 (linear voltage rise)}$                                            | $V_{DR} = \frac{2}{3} V_{DRM}$                                          | 1000<br>$\text{V}/\mu\text{s}$                                                           |
| $P_{GM}$                                     | $T_{VJ} = T_{VJM};$<br>$I_T = I_{TAVM};$                                                                                   | $t_p = 30 \mu\text{s}$<br>$t_p = 300 \mu\text{s}$                       | 10<br>5<br>W<br>W                                                                        |
| $P_{GAV}$                                    |                                                                                                                            |                                                                         | 0.5<br>W                                                                                 |
| $V_{RGM}$                                    |                                                                                                                            |                                                                         | 10<br>V                                                                                  |
| $T_{VJ}$                                     |                                                                                                                            |                                                                         | -40...+125<br>$^\circ\text{C}$                                                           |
| $T_{VJM}$                                    |                                                                                                                            |                                                                         | 125<br>$^\circ\text{C}$                                                                  |
| $T_{stg}$                                    |                                                                                                                            |                                                                         | -40...+125<br>$^\circ\text{C}$                                                           |
| $V_{ISOL}$                                   | 50/60 Hz, RMS;<br>$I_{ISOL} \leq 1 \text{ mA};$                                                                            | $t = 1 \text{ min}$<br>$t = 1 \text{ s}$                                | 3000<br>3600<br>V~<br>V~                                                                 |
| $M_d$                                        | Mounting torque (M5)<br>Terminal connection torque (M5)                                                                    |                                                                         | 2.5-4.0/22-35<br>2.5-4.0/22-35<br>$\text{Nm}/\text{lb.in.}$<br>$\text{Nm}/\text{lb.in.}$ |
| Weight                                       | Typical including screws                                                                                                   |                                                                         | 90<br>g                                                                                  |

Data according to IEC 60747 and refer to a single thyristor/diode unless otherwise stated.

IXYS reserves the right to change limits, test conditions and dimensions

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### Features

- International standard package, JEDEC TO-240 AA
- Direct copper bonded  $\text{Al}_2\text{O}_3$  -ceramic base plate
- Planar passivated chips
- Isolation voltage 3600 V~
- UL registered, E 72873
- Gate-cathode twin pins for version 1B

### Applications

- DC motor control
- Softstart AC motor controller
- Light, heat and temperature control

### Advantages

- Space and weight savings
- Simple mounting with two screws
- Improved temperature and power cycling
- Reduced protection circuits

| Symbol             | Conditions                                                                                                                                                                              | Characteristic Values |                  |
|--------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------|------------------|
| $I_{RRM}, I_{DRM}$ | $T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$                                                                                                                                        | 5                     | mA               |
| $V_T / V_F$        | $I_T / I_F = 300 \text{ A}; T_{VJ} = 25^\circ\text{C}$                                                                                                                                  | 1.74                  | V                |
| $V_{T0}$           | For power-loss calculations only ( $T_{VJ} = 125^\circ\text{C}$ )                                                                                                                       | 0.85                  | V                |
| $r_T$              |                                                                                                                                                                                         | 3.2                   | m $\Omega$       |
| $V_{GT}$           | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$                                                                                                                                          | 2.5                   | V                |
|                    | $T_{VJ} = -40^\circ\text{C}$                                                                                                                                                            | 2.6                   | V                |
| $I_{GT}$           | $V_D = 6 \text{ V}; T_{VJ} = 25^\circ\text{C}$                                                                                                                                          | 150                   | mA               |
|                    | $T_{VJ} = -40^\circ\text{C}$                                                                                                                                                            | 200                   | mA               |
| $V_{GD}$           | $T_{VJ} = T_{VJM}; V_D = \frac{2}{3} V_{DRM}$                                                                                                                                           | 0.2                   | V                |
| $I_{GD}$           |                                                                                                                                                                                         | 10                    | mA               |
| $I_L$              | $T_{VJ} = 25^\circ\text{C}; t_p = 10 \mu\text{s}; V_D = 6 \text{ V}$<br>$I_G = 0.45 \text{ A}; di/dt = 0.45 \text{ A}/\mu\text{s}$                                                      | 450                   | mA               |
| $I_H$              | $T_{VJ} = 25^\circ\text{C}; V_D = 6 \text{ V}; R_{GK} = \infty$                                                                                                                         | 200                   | mA               |
| $t_{gd}$           | $T_{VJ} = 25^\circ\text{C}; V_D = \frac{1}{2} V_{DRM}$<br>$I_G = 0.45 \text{ A}; di/dt = 0.45 \text{ A}/\mu\text{s}$                                                                    | 2                     | $\mu\text{s}$    |
| $t_q$              | $T_{VJ} = T_{VJM}; I_T = 150 \text{ A}, t_p = 200 \mu\text{s}; -di/dt = 10 \text{ A}/\mu\text{s}$<br>$V_R = 100 \text{ V}; dv/dt = 20 \text{ V}/\mu\text{s}; V_D = \frac{2}{3} V_{DRM}$ | typ. 185              | $\mu\text{s}$    |
| $Q_S$              | $T_{VJ} = T_{VJM}; I_T / I_F = 50 \text{ A}, -di/dt = 6 \text{ A}/\mu\text{s}$                                                                                                          | 170                   | $\mu\text{C}$    |
| $I_{RM}$           |                                                                                                                                                                                         | 45                    | A                |
| $R_{thJC}$         | per thyristor/diode; DC current                                                                                                                                                         | 0.3                   | K/W              |
| $R_{thJK}$         | per module                                                                                                                                                                              | 0.15                  | K/W              |
|                    | per thyristor/diode; DC current                                                                                                                                                         | 0.5                   | K/W              |
|                    | per module                                                                                                                                                                              | 0.25                  | K/W              |
| $d_S$              | Creepage distance on surface                                                                                                                                                            | 12.7                  | mm               |
| $d_A$              | Strike distance through air                                                                                                                                                             | 9.6                   | mm               |
| $a$                | Maximum allowable acceleration                                                                                                                                                          | 50                    | m/s <sup>2</sup> |

Optional accessories for module-type MCC 72 version 1 B

Keyed gate/cathode twin plugs with wire length = 350 mm, gate = yellow, cathode = red

Type **ZY 200L** (L = Left for pin pair 4/5) } UL 758, style 1385,

Type **ZY 200R** (R = right for pin pair 6/7) } CSA class 5851, guide 460-1-1

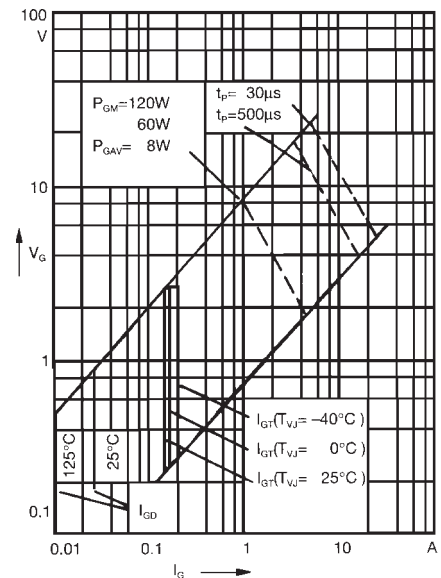


Fig. 1 Gate trigger characteristics

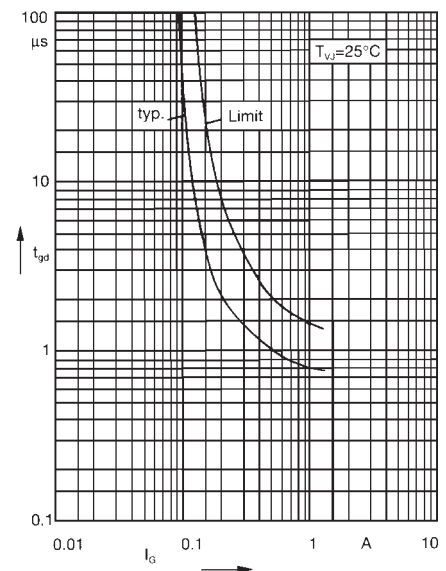
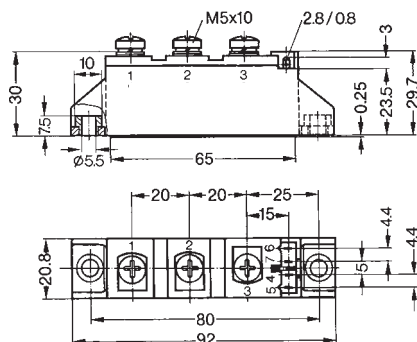


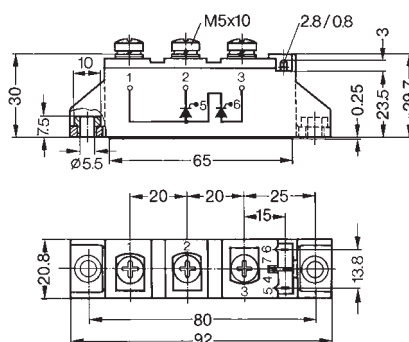
Fig. 2 Gate trigger delay time

Dimensions in mm (1 mm = 0.0394")

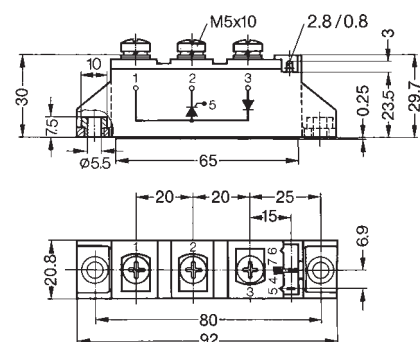
### MCC / MCD Version 1 B



### MCC Version 8 B



### MCD Version 8 B



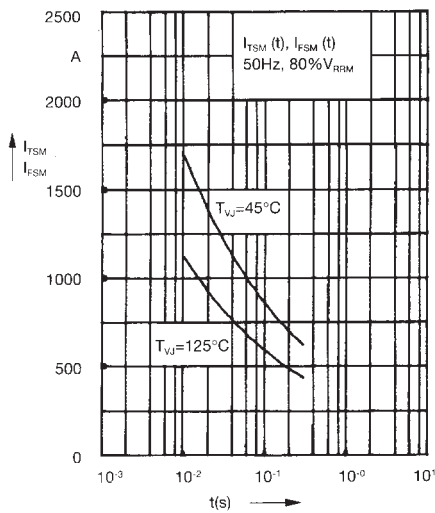


Fig. 3 Surge overload current  
 $I_{TSM}$ ,  $I_{FSM}$ : Crest value,  $t$ : duration

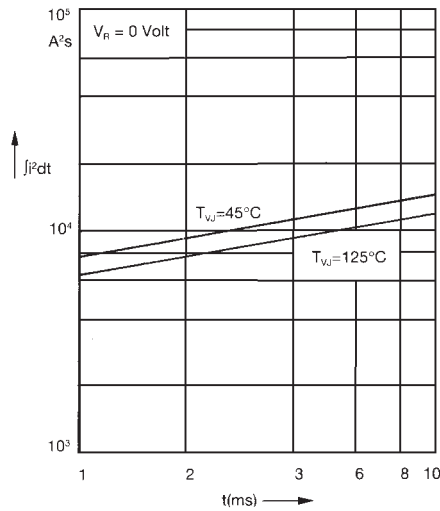


Fig. 4  $\int i^2 dt$  versus time (1-10 ms)

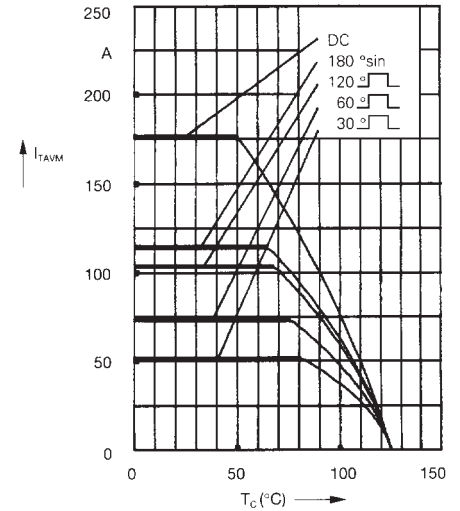


Fig. 4a Maximum forward current at case temperature

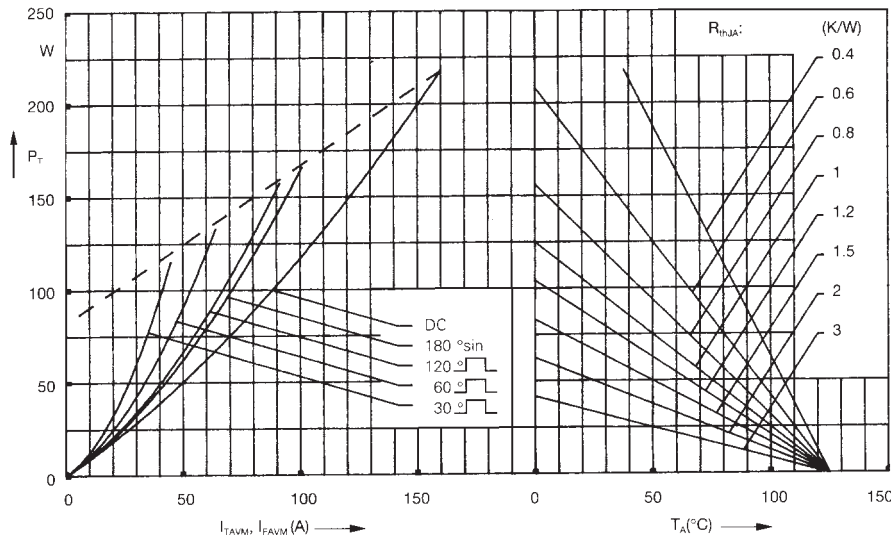


Fig. 5 Power dissipation versus on-state current and ambient temperature (per thyristor or diode)

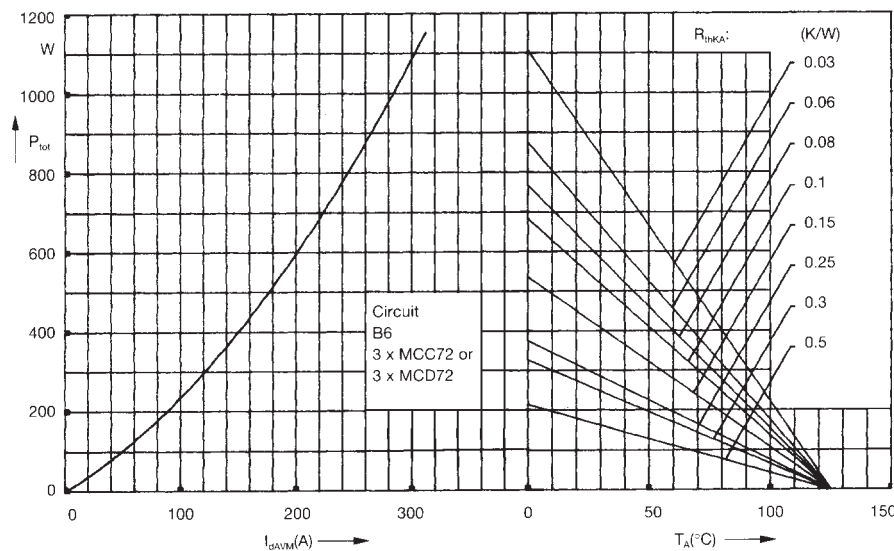


Fig. 6 Three phase rectifier bridge:  
Power dissipation versus direct output current and ambient temperature

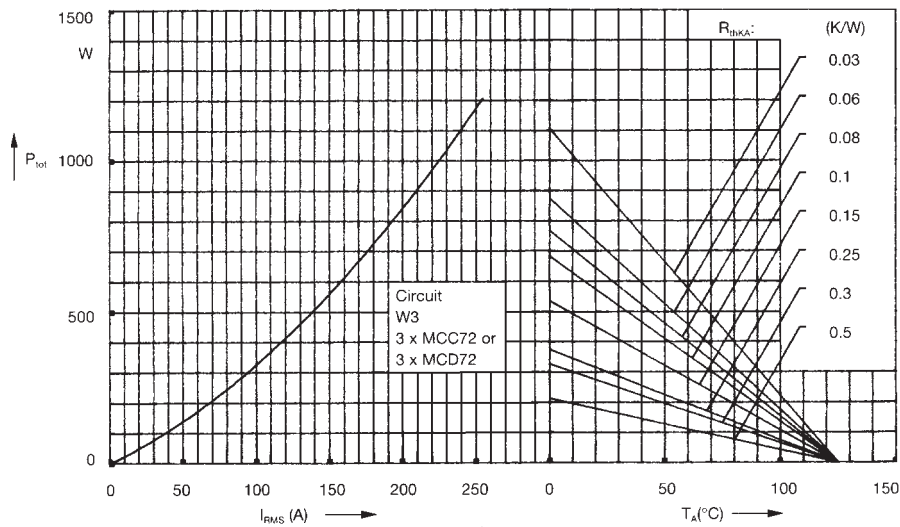


Fig. 7 Three phase AC-controller:  
Power dissipation versus RMS  
output current and ambient  
temperature

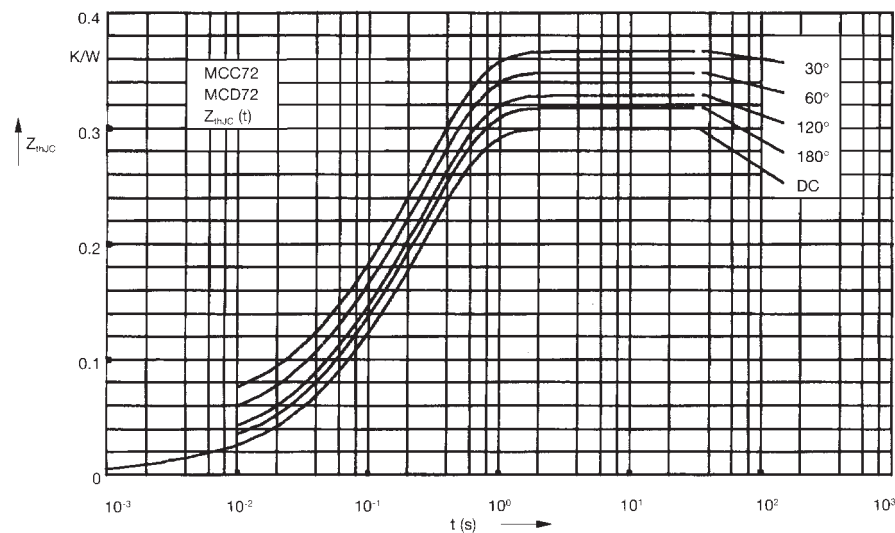


Fig. 8 Transient thermal impedance  
junction to case (per thyristor or  
diode)

$R_{thJC}$  for various conduction angles  $d$ :

| $d$  | $R_{thJC}$ (K/W) |
|------|------------------|
| DC   | 0.3              |
| 180° | 0.31             |
| 120° | 0.33             |
| 60°  | 0.35             |
| 30°  | 0.37             |

Constants for  $Z_{thJC}$  calculation:

| $i$ | $R_{thi}$ (K/W) | $t_i$ (s) |
|-----|-----------------|-----------|
| 1   | 0.008           | 0.0019    |
| 2   | 0.054           | 0.047     |
| 3   | 0.238           | 0.3       |

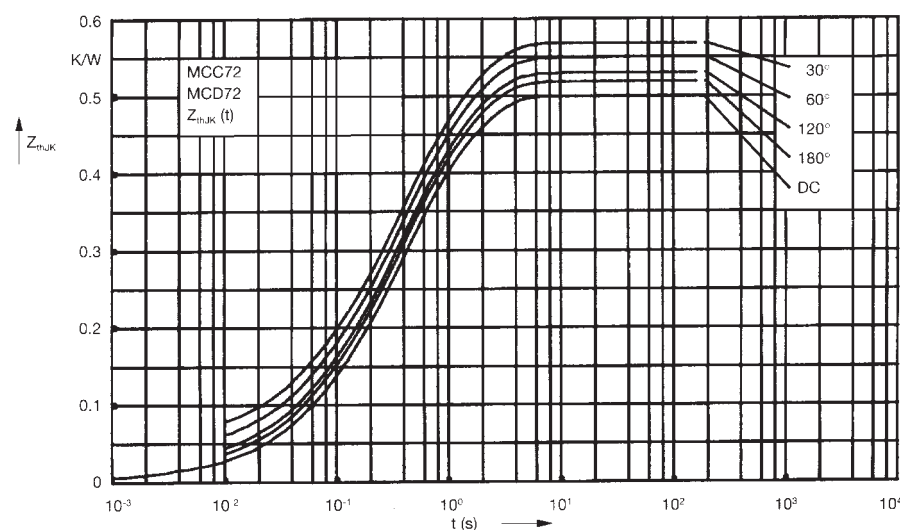


Fig. 9 Transient thermal impedance  
junction to heatsink (per thyristor  
or diode)

$R_{thJK}$  for various conduction angles  $d$ :

| $d$  | $R_{thJK}$ (K/W) |
|------|------------------|
| DC   | 0.5              |
| 180° | 0.51             |
| 120° | 0.53             |
| 60°  | 0.55             |
| 30°  | 0.57             |

Constants for  $Z_{thJK}$  calculation:

| $i$ | $R_{thi}$ (K/W) | $t_i$ (s) |
|-----|-----------------|-----------|
| 1   | 0.008           | 0.0019    |
| 2   | 0.054           | 0.047     |
| 3   | 0.238           | 0.3       |
| 4   | 0.2             | 1.25      |